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A Las Vegas Algorithm
for
Linear Programming
When the Dimension is Small

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Outline

- Results
- The smallest enclosing sphere
 - the algorithm
 - analysis of the algorithm
- Modifications for LP
- Conclusions

Problem: linear programming with n inequality constraints in d variables,

- $O(n2^{2^d})$ [Meg];
- $O(n3^{d^2})$ [C][D];
- $O(nd^{3d+\epsilon})$ Las Vegas [DF];

New bound:

$$O(d^2n) + O(d \log n)O(d)^{d/2+O(1)}$$

expected arithmetic operations, Las Vegas.

Time bound from

$O(d \log n)$ calls to simplex,
on subproblems with $\approx d^2$ constraints.

The smallest enclosing sphere

Given

$S \subset E^d$ of size n , in general position,
find $B^*(S)$,
the smallest closed ball containing S .

Facts: $B^*(S)$ exists, is unique,
and there exists $S^* \subset S$ with
 $|S^*| \leq d + 1$ and $B^*(S^*) = B^*(S)$.

The algorithm

The general idea: focus in on S^* using random sampling.

choose random $R \subset S$ with $|R| = 2(d + 1)^2$;
compute $B^*(R)$ using some algorithm;
Let $V \leftarrow S \setminus B^*(R)$;

Fact: V contains at least one point of S^*
(unless $B^*(R) = B^*(S)$ so $V = \phi$)

Otherwise $S^* \subset B^*(R)$,
with $B^*(R)$ no larger than $B^*(S)$;
So $B^*(R) = B^*(S^*) = B^*(S)$;

Fact: The expected size of V is
 $(d + 1)n/r = n/2(d + 1)$.

So V is a small set that must contain a member of S^* .

An iterative algorithm

$w_p \leftarrow 1$ for all $p \in S$;

repeat

 choose (weighted) random $R \subset S$;

$V \leftarrow S \setminus B^*(R)$;

$w_p \leftarrow 2w_p$ for all $p \in V$;

until $V = \phi$

Compare the total weight of S
with the total weight of S^* ;

Each time,
some point in S^* is in V .

After $k(d + 1)$ th step, weight of S^* is at least
 $(d + 1)2^k$;

Each iteration, expected weight of V is dW/r
 W is the current weight, at first $W = n$.

The next weight is $W(1 + (d + 1)/r)$;

After $k(d + 1)$ th step,

$$W \leq n(1 + (d + 1)/r)^{k(d+1)} \approx ne^{k/2}.$$

With $k = O(\log n)$, algorithm will stop.

Proof that the expected size of V is $(d + 1)n/r = \sqrt{n}$:

Let \mathcal{F}_S denote $\{B^*(T) \mid T \subset S\}$

For $B \in \mathcal{F}_S$, let T_B be

the smallest $T \subset S$ with $B = B^*(T)$. Then

$|T_B| \leq d + 1$ for $B \in \mathcal{F}_S$.

Let $\mathcal{F}_S^j = \{B \in \mathcal{F}_S \mid j = |S \setminus B|\}$.

Similarly define $\mathcal{F}_R, \mathcal{F}_R^j$.

Note that $\mathcal{F}_S^0 = \{B^*(S)\}$.

Fact: $|\mathcal{F}_S^1| \leq d + 1$.

Proof of claim:

Let $I_B = 1$ when $B = B^*(R)$, 0 otherwise.

The expected number of points outside $B^*(R)$ is

$$\begin{aligned}
E \left[\sum_{\substack{j \geq 0 \\ B \in \mathcal{F}_S^j}} I_B j \right] &= \sum_{\substack{j \geq 0 \\ B \in \mathcal{F}_S^j}} E[I_B] j = \sum_{\substack{j \geq 0 \\ B \in \mathcal{F}_S^j}} \text{Prob}\{B = B^*(R)\} j \\
&= \sum_{\substack{j \geq 0 \\ B \in \mathcal{F}_S^j}} \binom{n-j-|T_B|}{r-|T_B|} j / \binom{n}{r} \\
&\leq \frac{n-r+d+1}{r-d-1} \sum_{\substack{j \geq 0 \\ B \in \mathcal{F}_S^j}} \binom{n-j-|T_B|}{r-|T_B|-1} j / \binom{n}{r} \\
&\leq (n/r) \sum_{j \geq 0, B \in \mathcal{F}_S^j} \text{Prob}\{B \in \mathcal{F}_R^1\} \\
&= (n/r) E[|\mathcal{F}_R^1|] = \frac{n}{r} (d+1).
\end{aligned}$$

Modifications for LP

$\max\{cx \mid Ax \leq b\},$
where A is $n \times d$

a similar algorithm, except:

- sample constraint inequalities, not points
- modify to assure feasibility
- give answers for unbounded subproblems
- break ties by choosing shortest optimal point
- use simplex for base case

Concluding Remarks

- What about small n/d ?
- Any implications for simplex?
- Any implications for combinatorial problems?